

# Modulo Scheduling with Regular Unwinding

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We introduce a new technique for modulo scheduling, based on the unwinding of the modulo scheduling problem, and the acyclic scheduling of the unwinded problem under an additional constraint of regularity. Given  $\lambda$  the modulo schedule initiation interval, a regular unwinded schedule is such that two successive instances of any operation are scheduled at least  $\lambda$  cycles apart. For a given  $\lambda$ , we establish the equivalence between the modulo schedules, and the regular unwinded schedules of suitable size.

A main benefit of the regular unwinding technique is the re-formulation of the modulo scheduling problems in the classic framework of acyclic scheduling. In particular, we introduce new modulo scheduling problem relaxations that are solvable in pseudo-polynomial time. These results are obtained by combining regular unwinding with the time-constrained instruction scheduling relaxation of Leung, Palem & Pnueli [2].

*Modulo scheduling* [3, 1] is an instruction scheduling technique used for software pipelining inner program loops. In modulo scheduling problems, a set of operations  $\{O_i\}_{1 \leq i \leq n}$  is repeatedly executed with a period of  $\lambda$  cycles, the *initiation interval*. Precisely, we denote  $\{\sigma_i\}_{1 \leq i \leq n}$  the schedule dates, and the execution is constrained as follows:

- Uniform dependence constraints denoted  $O_i \xrightarrow{\alpha_i^j, \beta_i^j} O_j$ : for each such dependence, a valid modulo schedule satisfies  $\sigma_i + \alpha_i^j - \lambda\beta_i^j \leq \sigma_j$ . The *latency*  $\alpha_i^j$  and the *distance*  $\beta_i^j$  of the dependences are non negative integers. The *carried* dependences are such that  $\beta_i^j > 0$ .
- Modulo resource constraints: each operation  $O_i$  requires  $\vec{b}_i \geq \vec{0}$  cumulative resources for all the time intervals  $[\sigma_i + k\lambda, \sigma_i + k\lambda + p_i - 1], k \in \mathbb{Z}$ , and the total resource use at any time

must not exceed  $\vec{B}$ . The positive integer value  $p_i$  is the processing time of operation  $O_i$ .

## References

- [1] M. LAM: *Software Pipelining: an Effective Scheduling Technique for VLIW Machines* SIGPLAN Conference on Programming Language design and Implementation – PLDI'88, June 1988.
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- [3] B. R. RAU , C. D. GLAESER: *Some Scheduling Techniques and an Easily Schedulable Horizontal Architecture for High Performance Scientific Computing* 14th Annual Microprogramming Workshop on Microprogramming – MICRO-14, Dec. 1981.